Easy way to Conical Intersections

Alexander A. Granovsky

Laboratory of Chemical Cybernetics M.V. Lomonosov Moscow State University, Moscow, Russia November 12th, 2008

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Approaches to Conical Intersections (CIs) studies

 State-averaged (SA) -MCSCF is the most widely used approach as of yet
 It's the only approach considered in this presentation

What we actually need:

CI location

- $E_i = E_j, E_i = min$
- One needs at least state-specific (SS) gradients for states of interest within the SA-MCSCF framework
- If searching for CIs using non-adiabatic basis, one needs gradient of non-adiabatic coupling constant as well. However, one can avoid this by applying adiabatic basis

Excited states optimization

- $E_i = min$
- One needs SS gradients for states of interest within the SA-MCSCF framework

Our goal

– SS gradients for SA-MCSCF

Basics of molecular gradients theory

• E = E(C, c, I), where

- C is the matrix of MO coefficients

- c are the coefficient of "wavefunction" expansion over CSFs or determinants
- I are 1-e and 2-e integrals in AO basis
- $dE / dx = \partial E / \partial C \cdot \partial C / \partial x + \partial E / \partial \mathbf{c} \cdot \partial \mathbf{c} / \partial x + \partial E / \partial I \cdot \partial I / \partial x$
 - basic equation of gradient theory

SS-MCSCF case

- $dE / dx = \partial E / \partial C \cdot \partial C / \partial x + \partial E / \partial \mathbf{c} \cdot \partial \mathbf{c} / \partial x + \partial E / \partial I \cdot \partial I / \partial x$
 - $\partial E / \partial C = 0$
 - $\partial E / \partial \mathbf{c} = 0$
- Thus: $dE / dx \equiv \partial E / \partial I \cdot \partial I / \partial x$ – Just like for HF itself
- The theory of molecular gradients is very simple for SS-MCSCF!
 - the implementation is very straightforward and efficient as well

SA-MCSCF case

 $\frac{\partial E_i}{\partial x} = \frac{\partial E_i}{\partial C} \cdot \frac{\partial C}{\partial x} + \frac{\partial E_i}{\partial c_i} \cdot \frac{\partial c_i}{\partial x} + \frac{\partial E_i}{\partial i_i} - \frac{\partial E}{\partial c_i} = 0 \text{ but } \frac{\partial E_i}{\partial c_i} = 0 \text{ }$ $= \frac{\partial E_i}{\partial c_i} = 0 \text{ }$

• Thus: $dE_i / dx = \partial E_i / \partial C \cdot \partial C / \partial x + \partial E_i / \partial I \cdot \partial I / \partial x$

- Much more difficult case to handle
- Formally we need to solve MC-CPHF equations for z-vector to find MOs response terms
 - Need much wider class of transformed 2-e integrals
 - less efficient and slower integral transformation with possible integral sorting step
 - perhaps much longer step than MCSCF itself, esp. for large problems
 - Need to set up and solve large system of linear equations
 - Need to handle MCSCF of different types separately (e.g., 7 CASSCF would be the special case)

I'm too lazy actually...

Are there any alternative ways to go?
 Indeed they are...

The approach

SA-MCSCF:

$$- E = \sum_{i} w_i E_i = E(\overline{w}, C, \mathbf{c}, I)$$

 $\frac{dE}{dw_i} = E_i$

$$- \frac{\partial E}{\partial w_i} = E$$

 $-\frac{dE}{dw_{i}} = \frac{\partial E}{\partial w_{i}} + \frac{\partial E}{\partial C} \cdot \frac{\partial C}{\partial w_{i}} + \frac{\partial E}{\partial \mathbf{c}} \cdot \frac{\partial \mathbf{c}}{\partial \mathbf{c}} \cdot \frac{\partial \mathbf{c}}{\partial w_{i}} + \frac{\partial E}{\partial I} \cdot \frac{\partial I}{\partial W_{i}}$

• where: $\partial E / \partial C \equiv 0$, $\partial E / \partial c \equiv 0$, and $\partial I / \partial w_i \equiv 0$

Finally:

The final step

Considering the following identity:

 $dE_i / dx = d(dE / dw_i) / dx = d^2E / dw_i dx = d(dE / dx) / dw_i$

we finally realize:

$\overline{g_i} = dE_i / dx = d\overline{g} / dw_i$

• where \overline{g} is gradient of the SA-MCSCF energy

How can we use this?

- The expression for g is very simple exactly the same as for SS-MCSCF case above
 - Any existing code capable to compute SS-MCSCF gradients can be used to compute gradient of SA-MCSCF energy as well
- The expression for weight derivatives is not simple at all
 - Actually we just do not need it
 - Let's differentiate with respect to weight numerically!
 - Practical approach use of three-point finite difference formulas
 - Straightforward extension to any derivatives of any order, e.g., Hessians, response-type multipole moments, polarizabilities, etc...

So what we got is:

Traditional approach

- Solve SA-MCSCF problem
- Calculate SS gradient
 - Integral transformation
 - Solve MC-CPHF equations
 - And finally, gather all contributions to SS gradient, including AO part

Our approach

- Solve two or three SA-MCSCF problems
- Calculate SA gradient two (central differencing formulas) or three (non-symmetric formulas) times
 The rest is just a simple math

Is this affordable?

Computational demands

- Our way is the fastest possible for large AO basis sets
 - Does not require large-scale four-center integrals transformation
 - Does not require solution of large system of linear equations
- Precision
 - Resulting approximate gradients are smooth functions of (geometric) parameters!
 - Numerous numerical experiments show that use of Δw of about 10⁻³ results in gradients of six-digits accuracy
 - Numerically stable
 - Enough for geometry optimization and Cls location
 - Enough for semi-numerical Hessians
 - Seems to be enough even for double-seminumerical Raman activities!

It's a little bit tricky however...

No known programs are capable to deal with SA-MCSCF energies and gradients in the case of nonunit sum of weights

- Simple solution to avoid code changes:
 - Perturb the weights
 - Normalize them back
 - Perform calculation
 - Renormalize the answer
- Extra high precision is needed while solving SA-MCSCF problem
 - It's easy, fast, and efficient with PC GAMESS/Firefly
 - For standard way, we would need some extra precision as well

It's a little bit tricky however...

Excited states geometry optimization

- No (quasi) degeneracy in most cases

Central (symmetric) finite difference formula is the best

- Is numerically stable
- Requires only two SA gradient calculations per SS gradient
- Somewhat higher precision

Cls location

- Near or at (quasi) degeneracy
- Central finite difference formula is not applicable anymore
 - Is not numerically stable because SA-MCSCF may have multiple solutions (branches) for slightly differently "weighted" calcs.
 - Use of one-sided finite differencing formulas solves the problem!
 - Minor overhead third SA gradient calculation is required 15

Concluding remark

CI location

- Most common situation two-state averaged MCSCF
 - We do not need six MCSCF computations to find two SS gradients
 - All the required information can be obtained while computing SS gradients for any single state

Thank you for your attention!