Exploiting non-Abelian symmetry in AO-driven CIS, RPA, and TDDFT calculations

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#### An efficient implementation of time-dependent density-functional theory for the calculation of excitation energies of large molecules

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#### Adiabatic time-dependent density functional methods for excited state properties

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#### **RPA & TDDFT** master equation

The basic statement is that excitation energies are the stationary points of the functional

$$G[X,Y,\Omega] = \langle X,Y | \Lambda | X,Y \rangle - \Omega(\langle X,Y | \Delta | X,Y \rangle - 1). \quad (1)$$

 $\boldsymbol{\Omega}$  is a real Lagrange multiplier, and the vectors

$$|X,Y\rangle = \begin{pmatrix} X \\ Y \end{pmatrix} \tag{2}$$

are defined on the Hilbert space  $L = L_{virt} \times L_{occ} \oplus L_{occ} \times L_{virt}$ , where  $L_{occ}$  and  $L_{virt}$  denote the Hilbert spaces of occupied (occ) and virtual (virt) molecular orbitals (MOs), respectively. The MOs  $\varphi_{p\sigma}(\mathbf{r})$  are solutions of the static KS equations with eigenvalues  $\epsilon_{p\sigma}$ . As usual, indices i,j,... label occupied, a,b,... virtual, and p,q,... general MOs. We assume the MOs to be real, which is always possible in the absence of magnetic fields.

# **RPA & TDDFT** master equation

The "superoperators"  $\Lambda$  and  $\Delta$ 

read

$$\Lambda = \begin{pmatrix} A & B \\ B & A \end{pmatrix}, \quad \Delta = \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix}.$$
(3)

A and B are sometimes called orbital rotation Hessians

#### A and B matrices

$$(A+B)_{ia\sigma jb\sigma'} = (\epsilon_{a\sigma} - \epsilon_{i\sigma}) \,\delta_{ij} \delta_{ab} \delta_{\sigma\sigma'} + 2(ia\sigma|jb\sigma') + 2 f_{ia\sigma jb\sigma'}^{\text{xc}} - c_{x} \delta_{\sigma\sigma'} [(ja\sigma|ib\sigma) + (ab\sigma|ij\sigma)], (A-B)_{ia\sigma jb\sigma'} = (\epsilon_{a\sigma} - \epsilon_{i\sigma}) \,\delta_{ij} \delta_{ab} \delta_{\sigma\sigma'} + c_{x} \delta_{\sigma\sigma'} [(ja\sigma|ib\sigma) - (ab\sigma|ij\sigma)].$$

 $(pq\sigma|rs\sigma')$  is a two-electron repulsion integral in Mulliken notation, and  $f_{pq\sigma rs\sigma'}^{xc}$  represents a matrix element of the exchange-correlation kernel in the adiabatic approximation,

$$f_{\sigma\sigma'}^{\rm xc}(\mathbf{r},\mathbf{r}') = \frac{\delta^2 E^{\rm xc}}{\delta\rho_{\sigma}(\mathbf{r})\,\delta\rho_{\sigma'}(\mathbf{r}')}.$$

#### RPA & TDDFT master equation

Applying the variational principle, we obtain the stationarity conditions for G,

$$\frac{\delta G}{\delta \langle X, Y |} = (\Lambda - \Omega \Delta) | X, Y \rangle = 0,$$

$$\frac{\partial G}{\partial \Omega} = \langle X, Y | \Delta | X, Y \rangle - 1 = 0.$$

The CIS or Tamm–Dancoff approximation (TDA) is easily derived by constraining Y identically to zero in the variation of G.

#### How to solve?

#### 

 Davidson diagonalization vectors X RPA & TDDFT Davidson-like diagonalization methods ✦ Require construction of (A+B)•X, (A+B)•Y, (A-B)·X, (A-B)·Y products for trial vectors X and Y For our purposes, it is sufficient to consider in details CIS only.

#### **AO-driven CIS**

- Let us consider RHF-based CIS for simplicity
- Let us transform basis from determinants to SAPS (CSF) to solve separate problems for singlet states (and triplet states) and to avoid spin-orbitals.

#### $\blacksquare \mathbf{A} \cdot \mathbf{X} = \Sigma_{jb} \mathbf{A}_{ia,jb} \cdot \mathbf{X}_{jb}$

- $\bullet \mathbf{A_{ia,jb}} = (\varepsilon_a \varepsilon_i) \delta_{ij} \delta_{ab} + \dots$ 
  - The most efficient way to evaluate this part of the matrixvector product is to use MO basis.
- $A_{ia,jb} = ... + (ia|jb) + exchange-related terms$ 
  - The most efficient way to calculate these parts of matrix-vector product (most time-consuming step) is to use AO basis:
  - +  $\Sigma_{jb}(ia|jb)\cdot X_{jb} = \Sigma_{jb} \Sigma_{pqrs} C_{ip} C_{aq} C_{jr} C_{bs} (pq|rs)\cdot X_{jb} =$  $\Sigma_{pq} C_{ip} C_{aq} \Sigma_{rs} (pq|rs) \cdot (\Sigma_{jb} C_{jr} C_{bs} X_{jb})$

#### **AO-driven CIS benefits**

Does not require integral transformation

 applicable to very large systems
 simplifies use of molecular symmetry

 Is based on the construction of Fock-like matrices

 All known approaches used to solve large-scale SCF problems can be also used in the case of CIS

- Linear scaling
  - QFMM
  - Linear exchange

# Main CIS and SCF differences

CIS operates with non-symmetrical (square) density-like and Fock-like matrices

CIS results in non totally-symmetric density and Fock-like matrices. The symmetry is defined by the symmetry of the target CIS state Reminiscence. Use of molecular point group symmetry in SCF methods

■ At least two different ways:

Use of symmetrized AO basis functions and 2-e integrals

Use of petite AO integral list:

- Construction of the skeleton Fock matrix
- Projection/symmetrization to the totally symmetric irreducible representation at the end

# Symmetrization of Operator Matrix Elements

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Recently, Dupuis and King [1], following earlier work by Dacre [2], have presented a method for constructing the matrix representation, over an AO basis, of a toally symmetric operator  $\hat{O}$ , using only symmetry-distinct AO integrals. Such a totally symmetric operator  $\hat{O}$  satisfies the equation

$$\mathbf{R}^{\dagger}\mathbf{O}\mathbf{R}=\mathbf{O},\tag{1}$$

where **O** is the matrix of  $\hat{O}$  in the AO basis, and **R** is the matrix representation of the effect of  $\hat{R}$ , an operator from the molecular point group  $\mathcal{G}$ , on the AO basis  $\chi$ :

$$\hat{\mathbf{x}} = \mathbf{x} \mathbf{R}. \tag{2}$$

**R** is a nonunitary reducible representation matrix. Of course, in general, many operators are not totally symmetric.

#### Skeleton matrix symmetrization

Any one-electron operator O will transform as a particular row (say, the Kth) of a particular representation (say  $\Gamma$ ), that is,

$$\hat{O}_{K}^{\Gamma} = \sum_{\Lambda} \mathscr{D}_{K\Lambda}^{\Gamma}(R)^{*} \hat{R}^{-1} \hat{O}_{\Lambda}^{\Gamma} \hat{R}.$$
(5)

In matrix form we then have

$$\mathbf{O}(\Gamma, K) = \sum_{\Lambda} \mathscr{D}_{K\Lambda}^{\Gamma}(R)^* \mathbf{R}^{\dagger} \mathbf{O}(\Gamma, \Lambda) \mathbf{R}.$$
 (6)

Here  $\Lambda$  runs over all partners in representation  $\Gamma$  and  $\mathcal{D}^{\Gamma}(R)$  is a representation matrix. It should be noted that  $\Gamma$  is *not* required to be irreducible but can always be taken as unitary.

We define symmetrization of an operator matrix  $O(\Gamma, K)$  by

$$\mathbf{O}(\Gamma, K)_{\text{sym}} = (2g)^{-1} \sum_{R} \sum_{\Lambda} \mathscr{D}_{K\Lambda}^{\Gamma}(R)^* R^{\dagger} [\mathbf{O}(\Gamma, \Lambda) + p\mathbf{O}(\Gamma, \Lambda)^{\dagger}] \mathbf{R}, \qquad (11)$$

where p = +1 if the operator is Hermitian and p = -1 if it is anti-Hermitian. We wish to establish the following

Theorem:

$$\mathbf{O}(\Gamma, K) = \bar{\mathbf{O}}(\Gamma, K)_{\text{sym}}$$
  
=  $(2g)^{-1} \sum_{R} \sum_{\Lambda} \mathscr{D}_{K\Lambda}^{\Gamma}(R)^* \mathbf{R}^{\dagger} \{ \bar{\mathbf{O}}(\Gamma, \Lambda) + p \bar{\mathbf{O}}(\Gamma, \Lambda)^{\dagger} \} \mathbf{R}.$  (12)

# Terminology

#### **Projection and Shift Operators**

An operator

$$\mathscr{P}^{\alpha}_{ii} = g^{-1} n_{\alpha} \sum_{G} D^{\alpha}_{ii}(G)^* G$$

is a *projection operator* or *projector*. It is Hermitian and idempotent. For  $i \neq j$  we have a *shift operator* 

$$\mathscr{P}^{\alpha}_{ji} = g^{-1} n_{\alpha} \sum_{G} D^{\alpha}_{ji}(G)^* G.$$

• For a projection operator

$$\mathscr{P}^{\alpha}_{ii}f = f^{\alpha}_i \text{ (or 0)},$$

whereas

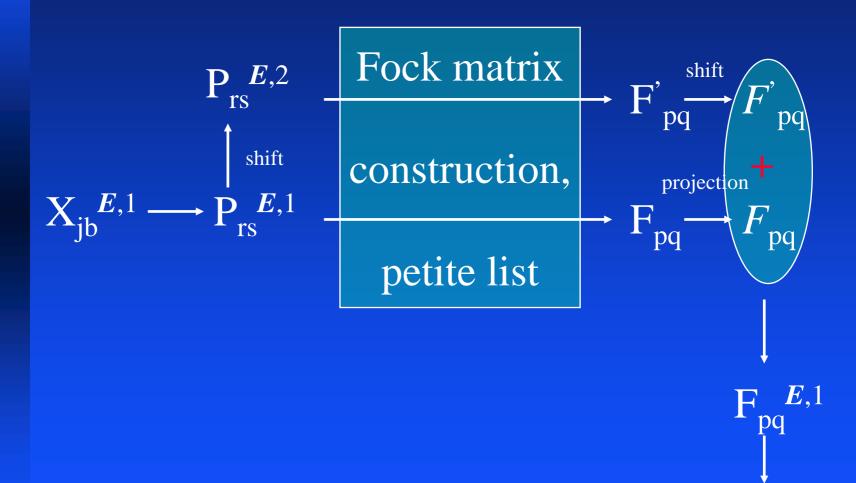
$$\mathscr{P}^{\alpha}_{ji}f^{\alpha}_i = f^{\alpha}_j.$$

That is, we obtain *partner functions* of  $f_i^{\alpha}$ .

#### Gathering things together

- Now we have all the tools to construct algorithm for (any symmetry) Fock-like matrix assembly using petite integral list
   Let us consider some 2-d irrep. *E* without the loss of generality.
- We are interested in getting CIS states transforming, say, as the first row of *E* only, as their counterparts can be constructed (if needed at all) after diagonalization of the CIS Hamiltonian using shift operators.

### Strategy



 $\mathbf{A} \cdot \mathbf{X}^{E,1}$ 

### The only nontrivial (?) point

Shift and projection operators for densitylike matrices are not the same as for Focklike matrices!

Fock-like matrices:

**→ R**(g)

Density-like matrices:

 $\mathbf{R}(g)$  should be replaced by  $\mathbf{R}^+(g^{-1})$ 

### Thank you for your attention!